

COMPARISON PRINCIPLE FOR ELLIPTIC EQUATIONS IN DIVERGENCE WITH SINGULAR LOWER ORDER TERMS HAVING NATURAL GROWTH

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ABSTRACT. In this paper we are concerned with the zero Dirichlet boundary value problem associated to the quasilinear elliptic equation

$$-\operatorname{div}(a(u)M(x)\nabla u) + H(x, u, \nabla u) = f(x), \quad x \in \Omega,$$

where Ω is an open and bounded set in \mathbb{R}^N ($N \geq 3$), a is a continuously differentiable real function in $(0, +\infty)$, $M(x)$ is an elliptic, bounded and symmetric matrix, $H(x, \cdot, \xi)$ is nonnegative and may be singular at zero and $f \in L^1(\Omega)$. We give sufficient conditions on H , M and a in order to have a comparison principle and, as a consequence, uniqueness of positive solutions being continuous up to the boundary.

1. INTRODUCTION

Let Ω be an open and bounded set in \mathbb{R}^N ($N \geq 3$) and $f \in L^1(\Omega)$. We consider the following boundary value problem

$$(1.1) \quad \begin{cases} -\operatorname{div}(a(u)M(x)\nabla u) + H(x, u, \nabla u) = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where $M(x)$ is a symmetric matrix satisfying, for some $\alpha, \beta > 0$, that

$$(1.2) \quad \alpha|\xi|^2 \leq M(x)\xi \cdot \xi \leq \beta|\xi|^2, \quad \forall \xi \in \mathbb{R}^N.$$

The function $a : (0, +\infty) \rightarrow \mathbb{R}$ is continuously differentiable and positive and $H : \Omega \times (0, +\infty) \times \mathbb{R}^N \rightarrow \mathbb{R}$ is a nonnegative Carathéodory function such that for a.e. $x \in \Omega$, $H(x, \cdot, \cdot)$ is continuously differentiable and

$$(1.3) \quad H(x, s, t\xi) = t^2H(x, s, \xi), \quad \forall s > 0, \forall t \in \mathbb{R}, \forall \xi \in \mathbb{R}^+.$$

A comparison principle for general differential operators of the form

$$-\operatorname{div}(a(x, u, \nabla u)) + H(x, u, \nabla u)$$

is established in [6, Theorem 1.2, Theorem 2.1 and Theorem 2.3 for the bounded case]. In the case $a(x, s, \xi) = \xi$, conditions imposed to H in [6] imply in particular that $\partial_s H \geq 0$. Moreover, as it was observed in Remark 2.5 of that paper, the maximum principle still holds in various situations even when $\partial_s H < 0$ and it would be desirable to find convenient structure conditions on H including some particular cases where $\partial_s H < 0$. A slightly improvement of these conditions can be found in [5] for f small enough and, once again, it is required that $\partial_s H \geq 0$.

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A different kind of comparison principle is proved in [4] where $M(x) = I$, the identity matrix, and $H(x, u, \nabla u) = g(u)|\nabla u|^2$ for some nonnegative continuous function g in $(0, +\infty)$. In this case, the authors imposed the integrability of $\frac{g(s)}{a(s)}$ at zero. This result handles the case that g is singular at zero (which necessarily implies that $\partial_s H \not\geq 0$). However, their techniques require strongly that the function H and the differential operator do not depend on x .

Some further extension, dealing with uniqueness, was done in [2] in the case $a(s) = 1$, $M(x) = I$ and $H(x, u, \nabla u) = -d(x)u - \mu(x)|\nabla u|^2 - h(x)$ for some $d, h \in L^p(\Omega)$, $p > N/2$, $d \leq 0$ and $\mu \in L^\infty(\Omega)$ (see [3] for an slightly improvement with general $M(x)$ and more general function H non decreasing on the variable s). It is once again imposed that $\partial_s H \geq 0$. Moreover, in some particular cases, with $\partial_s H < 0$ ($d(x) > 0$) they prove a multiplicity result (see Theorem 1.3 in [2]), that is, no uniqueness result is expected imposing only that $\partial_s H < 0$.

More recently, in [1] it is proved a comparison principle for (1.1) in the case $a(s) = 1$ and $M(x) = I$ for a particular class of functions $H(x, u, \nabla u)$ which are continuous at $u = 0$ and that may be decreasing on u .

The aim of this paper is to improve the above comparison principles in some directions: general matrices $M(x)$, dependence on x and singularity at $u = 0$ on the gradient quadratic part.

Let us illustrate our main result in the case $H(x, s, \xi) = h(x, s)|\xi|^2$, although we give a more general structure condition for H in section 2. More precisely, consider the boundary value problem:

$$(1.4) \quad \begin{cases} -\operatorname{div}(a(u)M(x)\nabla u) + h(x, u)|\nabla u|^2 = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

for a differentiable Carathéodory function h defined in $\Omega \times (0, +\infty)$ (i.e., a Carathéodory function such that $h(x, \cdot)$ is derivable for a.e. $x \in \Omega$).

We say that $u \in H_0^1(\Omega)$ with $u > 0$ is a subsolution (respectively, a supersolution) of (1.4) if $a(u)M(x)\nabla u \in L^2(\Omega)^N$, $h(x, u)|\nabla u|^2 \in L^1(\Omega)$ and

$$\int_{\Omega} a(u)M(x)\nabla u \nabla \phi + \int_{\Omega} h(x, u)|\nabla u|^2 \phi \leq \int_{\Omega} f \phi, \quad \forall \phi \in H_0^1(\Omega) \cap L^\infty(\Omega)$$

(respectively, if the reverse inequality holds). Thus, u is called a solution provided that it is both a subsolution and a super solution. We prove the following theorem.

Theorem 1.1. *Assume (1.2) and that for every $\nu > 0$ there exist $\theta \geq 0$ and a nonnegative function $g \in C^1((0, +\infty))$ with $a(s)e^{-\int_1^s \frac{g(t)}{a(t)} dt} \in L^1(0, 1)$ such that for a.e. $x \in \Omega$ and for every $0 < s < \nu$, the matrix*

$$(1.5) \quad \theta[a(s)\partial_s(h(x, s)I - g(s)M(x)) + (g(s) - 2a'(s))(h(x, s)I - g(s)M(x)) - M^{-1}(x))(h(x, s)I - g(s)M(x))^2]$$

is positive semidefinite. If $0 < v_1, v_2 \in H_0^1(\Omega) \cap C(\overline{\Omega})$ are respectively a sub and a supersolution for (1.4) then $v_1 \leq v_2$. As a consequence, we have uniqueness of $C(\overline{\Omega})$ solutions of (1.4). \square

Observe that if we assume that $f \in L^q(\Omega)$ for some $q > N/2$, $\inf a > 0$ and $\partial\Omega$ is smooth enough, in the sense of condition (A) in [7, p. 6], we have (see [7, Theorems 6.1 and 7.1 of Chapter 2]) that any solution of (1.1) belongs to $C(\overline{\Omega})$.

Hence with this assumption on the smoothness of the boundary we would obtain from the above theorem uniqueness of solutions of (1.4).

We prove in Section 2 a more general result than the above theorem. In Section 3 some corollaries (see Corollary 3.1, 3.2 and 3.5) of Theorem 1.1 are obtained when the term $h(x, s)$ is not necessary increasing in s and either nonsingular or singular. In particular, special emphasis will be put in the singular case. Indeed, we show (Corollary 3.5), as an application of the theorem that if $a(s) = 1$, $M(x) = I$ and $h(x, s) = \mu(x)/s^\gamma$ with $0 < \mu_1 \leq \mu(x) \leq \mu_2$ and $0 < \gamma < 1$, that the comparison principle holds. This improves [4] since dependence on x is allowed in $\mu(x)$. Even more, if $\mu(x)$ is a constant $m < 1$, we also improve [4] since we can also handle (see Remark 3.4) the case $h(x, s) = m/s$ which was uncovered by [4].

2. COMPARISON PRINCIPLE

In this section we prove our main result. For the statement of our main result let us recall that $u \in H_0^1(\Omega)$ with $u > 0$ is a subsolution (respectively, a supersolution) of (1.1) if $a(u)M(x)\nabla u \in L^2(\Omega)^N$, $H(x, u, \nabla u) \in L^1(\Omega)$ and

$$\int_{\Omega} a(u)M(x)\nabla u \nabla \phi + \int_{\Omega} H(x, u, \nabla u)\phi \leq \int_{\Omega} f\phi, \quad \forall \phi \in H_0^1(\Omega) \cap L^\infty(\Omega)$$

(respectively, if the reverse inequality holds). If u is a subsolution and a supersolution then it is called a solution.

Theorem 2.1. *Assume (1.2), (1.3) and that for every $\nu > 0$ there exist $\theta \geq 0$ and a nonnegative function $g \in C^1((0, +\infty))$, with $a(s)e^{-\int_1^s \frac{g(t)}{a(t)} dt} \in L^1(0, 1)$, such that for almost everywhere $x \in \Omega$ and for every $0 < s < \nu$ and $\xi \in \mathbb{R}^N$*

$$(2.1) \quad a(s)(\partial_s H(x, s, \xi) - g'(s)M(x)\xi \cdot \xi) \\ + (g(s) - 2a'(s))(H(x, s, \xi) - g(s)M(x)\xi \cdot \xi) - \frac{1}{\theta}\Theta(x, s, \xi) \geq 0$$

where

$$\Theta(x, s, \xi) := \frac{1}{4}M^{-1}(x)(\partial_\xi H(x, s, \xi) - 2g(s)M(x)\xi) \cdot (\partial_\xi H(x, s, \xi) - 2g(s)M(x)\xi).$$

If $0 < v_1, v_2 \in H_0^1(\Omega) \cap C(\overline{\Omega})$ are respectively a sub and a supersolution for (1.1), then $v_1 \leq v_2$. As a consequence, we have uniqueness of $C(\overline{\Omega})$ -solution v of (1.1).

Proof. For every $s \geq 0$, we use the following notation $\gamma(s) = \int_1^s \frac{g(t)}{a(t)} dt$, $\psi(s) = \int_0^s a(t)e^{-\gamma(t)} dt$, and $G_\varepsilon(s) = (s - \varepsilon)^+$ ($\varepsilon > 0$). If $v_1, v_2 \in H_0^1(\Omega) \cap C(\overline{\Omega})$ are respectively a sub and a supersolution for (1.1), we define $w = \psi(v_1) - \psi(v_2)$.

We observe that, since $\psi \in C([0, +\infty))$ and v_1, v_2 are continuous up to the boundary, the function $G_\varepsilon(w)$ has compact support $\Omega_\varepsilon := \text{supp } G_\varepsilon(w)$ in Ω , for every $\varepsilon > 0$. Moreover, $e^{-\gamma(v_i)}, \gamma'(v_i), \psi'(v_i) \in L^\infty(\Omega_\varepsilon)$ for $i = 1, 2$ and, even more, $G_\varepsilon(w) \in L^\infty(\Omega)$. Fix $\nu > \max\{\|v_1\|_{C(\Omega)}, \|v_2\|_{C(\Omega)}\}$ and θ such that (2.1) is satisfied for every $0 < s < \nu$. Thus, if n is the integer part of $\theta + 1$, we can take $e^{-\gamma(v_1)}G_\varepsilon(w)^n$ as test function in the inequality satisfied by v_1 and $e^{-\gamma(v_2)}G_\varepsilon(w)^n$

in the inequality satisfied by v_2 . Subtracting and taking into account (1.2) we have

$$\begin{aligned} 0 &\geq \int_{\Omega} \left(-\gamma'(v_1)\psi'(v_1)M(x)\nabla v_1 \cdot \nabla v_1 + H(x, v_1, \nabla v_1) \frac{\psi'(v_1)}{a(v_1)} \right) G_{\varepsilon}(w)^n \\ &\quad - \int_{\Omega} \left(-\gamma'(v_2)\psi'(v_2)M(x)\nabla v_2 \cdot \nabla v_2 + H(x, v_2, \nabla v_2) \frac{\psi'(v_2)}{a(v_2)} \right) G_{\varepsilon}(w)^n \\ &\quad + n \int_{\Omega} G_{\varepsilon}(w)^{n-1} M(x) (\psi'(v_1)\nabla v_1 - \psi'(v_2)\nabla v_2) \cdot \nabla w. \end{aligned}$$

By the homogeneity condition (1.3), if $s = \psi^{-1}(t\psi(v_1) + (1-t)\psi(v_2))$ and $\xi = t\nabla\psi(v_1) + (1-t)\nabla\psi(v_2)$, this means that

$$\begin{aligned} 0 &\geq \int_{\{w>\varepsilon\}} G_{\varepsilon}(w)^n \int_0^1 \frac{d}{dt} \left(\frac{-\gamma'(s)}{\psi'(s)} M(x)\xi \cdot \xi + \frac{H(x, s, \xi)}{a(s)\psi'(s)} \right) dt \\ &\quad + n \int_{\{w>\varepsilon\}} G_{\varepsilon}(w)^{n-1} M(x) \nabla w \cdot \nabla w. \end{aligned}$$

After deriving we get

$$\begin{aligned} 0 &\geq \int_{\{w>\varepsilon\}} w G_{\varepsilon}(w)^n \int_0^1 \frac{-g'(s)a(s) + 2g(s)a'(s) - g(s)^2}{a(s)^2\psi'(s)^2} M(x)\xi \cdot \xi dt \\ &\quad + \int_{\{w>\varepsilon\}} w G_{\varepsilon}(w)^n \int_0^1 \frac{\partial_s H(x, s, \xi)a(s) - H(x, s, \xi)(2a'(s) - g(s))}{a(s)^2\psi'(s)^2} dt \\ &\quad + \int_{\{w>\varepsilon\}} G_{\varepsilon}(w)^n \int_0^1 \left[\frac{-2g(s)M(x)\xi + \partial_{\xi} H(x, s, \xi)}{a(s)\psi'(s)} \right] \cdot \nabla w dt \\ &\quad + n \int_{\{w>\varepsilon\}} G_{\varepsilon}(w)^{n-1} M(x) \nabla w \cdot \nabla w. \end{aligned}$$

Multiplying by $\frac{\theta}{n}$ and taking into account that, by Young's inequality,

$$\begin{aligned} \frac{\theta}{n} \left| G_{\varepsilon}(w)^n \left[\frac{-2g(s)M(x)\xi + \partial_{\xi} H(x, s, \xi)}{a(s)\psi'(s)} \right] \cdot \nabla w \right| \\ \leq \frac{\theta^2}{n} G_{\varepsilon}(w)^{n-1} M(x) \nabla w \cdot \nabla w + \frac{G_{\varepsilon}(w)^{n+1}}{n} \frac{\Theta(x, s, \xi)}{a(s)^2\psi'(s)^2}, \end{aligned}$$

it follows by (1.2) that

$$\begin{aligned} 0 &\geq \alpha\theta \left(1 - \frac{\theta}{n} \right) \int_{\{w>\varepsilon\}} G_{\varepsilon}(w)^{n-1} |\nabla w|^2 \\ &\quad + \int_{\{w>\varepsilon\}} \int_0^1 \frac{w G_{\varepsilon}(w)^n \theta}{na^2(s)\psi'(s)^2} \left[\partial_s H(x, s, \xi)a(s) - H(x, s, \xi)(2a'(s) - g(s)) \right. \\ &\quad \left. + (-g'(s)a(s) + 2g(s)a'(s) - g(s)^2)M(x)\xi \cdot \xi - \frac{G_{\varepsilon}(w)}{\theta w} \Theta(x, s, \xi) \right] dt. \end{aligned}$$

Since $G_{\varepsilon}(w)/w \leq 1$, the integrand in the second integral is greater than zero by (2.1), and we deduce that the first integral is zero, which implies that $G_{\varepsilon}(w) = 0$ for every $\varepsilon > 0$, i.e., $w^+ = 0$, concluding the proof. \square

Remark 2.2. Since we consider the case of functions $H(x, \cdot, \xi)$ and $a(\cdot)$ that may be singular at zero, we have imposed the $C(\bar{\Omega})$ -regularity of the subsolution v_1 and the supersolution v_2 in the previous theorem. This regularity is just used to

guarantee that the function $e^{-\gamma(v_2)}(G_\varepsilon((\psi(v_1) - \psi(v_2))^+))^n$ has compact support (γ , ψ and n are introduced in the proof).

We observe that, when we only have that $v_1 \in H_0^1(\Omega) \cap L^\infty(\Omega)$ and $v_2 \in H_0^1(\Omega)$, the same proof works provided that the functions $e^{-\gamma(v_i)}((\psi(v_1) - \psi(v_2))^+)^n$, $\psi(v_i) \in H_0^1(\Omega)$, $i = 1, 2$. This is true, for example, if in (1.1) does not appear any singular term. Moreover, if $\frac{g(s)}{a(s)}$ and $a(s)$ are integrable at zero, a slightly modification can be performed in the proof by taking $e^{-\gamma(v_i+\varepsilon)}((\psi(v_1) - \psi(v_2))^+)^n \in H_0^1(\Omega)$ and passing to the limit as ε tends to zero to state the comparison principle for bounded sub and supersolutions.

Remark 2.3. As it has been observed just after Theorem 1.1, if $f \in L^q(\Omega)$ for some $q > N/2$, $\inf a > 0$ and $\partial\Omega$ is smooth then any solution of (1.1) belongs to $C(\bar{\Omega})$.

3. CONSEQUENCES

In this section we use Theorem 2.1 to prove a comparison principle for some model problems in which $H(x, s, \xi) = h(x, s)|\xi|^2$.

In this case, as it has been mentioned in the Introduction, Theorem 1.1 correspond to rewrite Theorem 2.1 into this context. As a first particular case of Theorem 1.1, we study the case in which $h(x, s)$ does not depends on s , i.e., $H(x, s, \xi) = \mu(x)|\xi|^2$ with $0 < \mu_1 \leq \mu(x) \leq \mu_2$ (notice that $\partial_s H = 0$ in this case).

Corollary 3.1. *Assume (1.2) and that $0 < \mu_1 \leq \mu(x) \leq \mu_2$, a.e. $x \in \Omega$. Suppose also that there exist positive real numbers a_1, a_2, a_3 such that*

$$(3.1) \quad 0 < a_1 \leq a(s), \quad -a_3 \leq a'(s) \leq a_2 < \frac{\mu_1}{2\beta}, \quad \forall s > 0.$$

If $0 < v_1, v_2 \in H_0^1(\Omega) \cap C(\bar{\Omega})$ are respectively a sub and a supersolution for

$$\begin{cases} -\operatorname{div}(a(u)M(x)\nabla u) + \mu(x)|\nabla u|^2 = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

then $v_1 \leq v_2$.

Proof. This is a direct consequence of Theorem 1.1 with $g(s) = m > 0$, for every $s > 0$, where $2a_2 < m < \frac{\mu_1}{\beta}$. Indeed, observe that $a(s)e^{-\int_1^s \frac{g(t)}{a(t)} dt} \in L^1(0, 1)$ by (3.1). In addition, from (1.2), there exists $\lambda > 0$ such that,

$$\begin{aligned} M^{-1}(x)(\mu(x)I - mM(x))^2\xi \cdot \xi &\leq \beta|M^{-1}(x)(\mu(x)I - mM(x))\xi|^2 \\ &\leq \beta(\mu_2^2|M^{-1}(x)|^2 + m^2 + 2m\mu_2|M^{-1}(x)|)|\xi|^2 \\ &\leq \beta(\mu_2^2\lambda^2 + m^2 + 2m\mu_2\lambda)|\xi|^2. \end{aligned}$$

Moreover, it follows that $(\mu(x)I - mM(x))\xi \cdot \xi \geq (\mu_1 - m\beta)|\xi|^2$. We deduce that if

$$\theta > \beta \frac{\mu_2^2\lambda^2 + m^2 + 2m\mu_2\lambda}{(m - 2a_2)(\mu_1 - m\beta)},$$

then

$$\theta(m - 2a'(s))(\mu(x)I - mM(x))\xi \cdot \xi \geq M^{-1}(x)(\mu(x)I - mM(x))^2\xi \cdot \xi, \quad \forall \xi \in \mathbb{R}^N,$$

which means that the matrix given by (1.5) is positive semidefinite in this case. \square

Similarly, we consider the case in which $h(x, s)$ depends only in s , that is, when $H(x, s, \xi) = h(s)\xi^2$.

Corollary 3.2. *Let (1.2) be satisfied and assume that there exist positive functions $a, h \in C^1((0, +\infty))$ and $c > 0$ such that $a(s)e^{-c \int_1^s \frac{h(t)}{a(t)} dt} \in L^1(0, 1)$ and for some $\tau > 0$*

$$(3.2) \quad \left(\frac{h'(s)}{h(s)^2} a(s) + c - \frac{2a'(s)}{h(s)} \right) (I - cM(x))\xi \cdot \xi \geq \tau|\xi|^2,$$

for every $s > 0$, $\xi \in \mathbb{R}^N$ and a.e. $x \in \Omega$. If $0 < v_1, v_2 \in H_0^1(\Omega) \cap C(\bar{\Omega})$ are respectively a sub and a supersolution for

$$\begin{cases} -\operatorname{div}(a(u)M(x)\nabla u) + h(u)|\nabla u|^2 = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

then $v_1 \leq v_2$.

Proof. The result is a direct consequence of Theorem 1.1 with $g(s) = ch(s)$, observe that $a(s)e^{-c \int_1^s \frac{h(t)}{a(t)} dt} \in L^1(0, 1)$. On the other hand, using (1.2), we deduce that there exists $\lambda > 0$ with

$$\begin{aligned} M^{-1}(x)(I - cM(x))^2\xi \cdot \xi &\leq \beta|M^{-1}(x)(I - cM(x))\xi|^2 \\ &\leq \beta(|M^{-1}(x)|^2 + c^2 + 2c|M^{-1}(x)|)|\xi|^2 \\ &\leq \beta(\lambda^2 + c^2 + 2c\lambda)|\xi|^2. \end{aligned}$$

Thus, if

$$\theta > \frac{\beta(\lambda^2 + c^2 + 2c\lambda)}{\tau},$$

then by (3.2) we have

$$(3.3) \quad \theta \left(\frac{h'(s)}{h(s)^2} a(s) + c - \frac{2a'(s)}{h(s)} \right) (I - cM(x))\xi \cdot \xi - M^{-1}(x)(I - cM(x))^2\xi \cdot \xi \geq 0,$$

which implies that, in this case, the matrix given by (1.5) is positive semidefinite and the proof is finished. \square

Remark 3.3. Observe that if $c < 1/\beta$, then $(I - cM(x))\xi \cdot \xi \geq (1 - c\beta)|\xi|^2 \geq 0$, while if $c > \frac{1}{\alpha}$ we have $(I - cM(x))\xi \cdot \xi \leq (1 - c\alpha)|\xi|^2 \leq 0$. Thus, condition (3.2) is satisfied provided that there exists a positive constant τ such that either

$$\left(\frac{h'(s)}{h(s)^2} a(s) + c - \frac{2a'(s)}{h(s)} \right) = - \left(\frac{a(s)^2}{h(s)} \right)' \frac{1}{a(s)} + c \geq \tau, \text{ if } c < \frac{1}{\beta},$$

or

$$\left(\frac{a(s)^2}{h(s)} \right)' \frac{1}{a(s)} - c \geq \tau, \text{ if } c > \frac{1}{\alpha}.$$

In particular, in the case $0 < c < 1/\beta$, hypothesis (3.2) is satisfied if the function $\frac{a(s)^2}{h(s)}$ is non increasing.

Remark 3.4. Although (3.2) is not satisfied, we observe that (3.3) in the proof of Corollary 3.2 is clearly satisfied in the case $a(s) = 1$, $M(x) = I$ with $c = 1$. In particular we can deduce that, if $h \in C^1((0, +\infty))$ is a positive function such that

$e^{-\int_1^s h(t)dt} \in L^1(0, 1)$ and $0 < v_1, v_2 \in H_0^1(\Omega) \cap C(\overline{\Omega})$ are respectively a sub and a supersolution for

$$\begin{cases} -\Delta u + h(u)|\nabla u|^2 = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

then $v_1 \leq v_2$. For example, we deduce the same comparison principle obtained in [4] for the case $h(s) = \frac{m}{s^\gamma}$ with $0 < \gamma < 1$ and $m > 0$. Even more, we can also deal with $h(s) = \frac{m}{s}$ with $0 < m < 1$.

The case in which the singularity is depending also on the x variable is particularly interesting. We obtain several improvements with respect to the singular problem studied in [4] where the authors assume that the quadratic part in ∇u does not depend on s . Specifically, we take $a(s) = 1$, $M(x) = I$, $H(x, s, \xi) = \mu(x) \frac{|\xi|^2}{s^\gamma}$ with $0 < \gamma < 1$, in order to study the problem

$$(3.4) \quad \begin{cases} -\Delta u + \mu(x) \frac{|\nabla u|^2}{u^\gamma} = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

Corollary 3.5. *Assume that $0 < \gamma < 1$, $0 < \mu(x) \in L^\infty(\Omega)$ and $0 \leq f \in L^1(\Omega)$. If $0 \leq v_1, v_2 \in H_0^1(\Omega) \cap C(\overline{\Omega})$ are respectively a sub and a supersolution for (3.4), then $v_1 \leq v_2$.*

Proof. Choose $0 < \gamma < d < 1$ and $C > 0$ such that

$$(3.5) \quad \|\mu\|_\infty \leq \min \left\{ dC, C \left(\frac{d-\gamma}{1-\gamma} \right)^{1-\gamma} \right\}.$$

Consider the function g given by

$$g(s) = \begin{cases} \frac{dC}{s^\gamma}, & s < \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \\ \frac{d\gamma}{\gamma s + \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} (1-\gamma)}, & s \geq \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}, \end{cases}$$

for every $s > 0$. Notice that $g \in C^1(0, +\infty)$ with

$$g'(s) = \begin{cases} -\frac{\gamma dC}{s^{\gamma+1}}, & s < \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \\ -\frac{d\gamma^2}{(\gamma s + \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} (1-\gamma))^2}, & s \geq \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}, \end{cases}$$

and $e^{-\int_1^s g(t)dt} \in L^1(0, 1)$. Thus, in order to apply Theorem 1.1 with this choice of function g , we just have to prove that for every $\nu > 0$ there exists $\theta > 0$ for which the matrix given by (1.5) is positive semidefinite for every $0 < s < \nu$ and a.e. $x \in \Omega$, or equivalently, that

$$(3.6) \quad s^{2\gamma} g'(s) + s^{2\gamma} g(s)^2 - s^\gamma \mu(x) g(s) + \gamma s^{\gamma-1} \mu(x) + \frac{1}{\theta} (\mu(x) - s^\gamma g(s))^2 \leq 0,$$

for every $0 < s < \nu$ and a.e. $x \in \Omega$.

To make it, we take for every fixed $\nu > 0$,

$$(3.7) \quad \theta > \max \left\{ \frac{dC + \|\mu\|_\infty}{C(1-d)}, \frac{2d(\|\mu\|_\infty^2 \nu^{2(1-\gamma)} + \gamma^2)}{(1-d)\gamma^2}, \frac{2\|\mu\|_\infty^2 \left(\frac{1-\gamma}{d-\gamma}\right)^{2(1-\gamma)} + 2d^2C^2}{d(1-d)C^2 \left(1 - \frac{\|\mu\|_\infty}{C} \left(\frac{1-\gamma}{d-\gamma}\right)^{1-\gamma}\right)} \right\}$$

and we show that (3.6) is satisfied by dividing the verification in three cases for $s \in (0, \beta)$:

i) If $s < \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}$, then

$$\frac{\gamma}{s^{1-\gamma}} - dC + \frac{1}{\theta}(\mu(x) - dC) \geq C - dC + \frac{1}{\theta}(\mu(x) - dC).$$

By (3.7), $\theta > \frac{dC - \mu(x)}{C - dC}$ and we deduce that

$$\frac{\gamma}{s^{1-\gamma}} - dC + \frac{1}{\theta}(\mu(x) - dC) > 0.$$

and, since $\|\mu\|_\infty \leq dC$ (by (3.5)), that

$$(\mu(x) - dC) \left(\frac{\gamma}{s^{1-\gamma}} - dC + \frac{1}{\theta}(\mu(x) - dC) \right) \leq 0,$$

which is (3.6) for $s \in \left(0, \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}\right)$.

ii) If $\left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \leq s \leq \frac{1-\gamma}{d-\gamma} \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}$, using that $(1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} s^{-1}$ is decreasing in s and that $\|\mu\|_\infty < C \left(\frac{d-\gamma}{1-\gamma}\right)^{1-\gamma}$, we have

$$\begin{aligned} (d-1)d\gamma^2 + \frac{\gamma\mu(x)}{s^\gamma} \left(\gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \right) \left(\gamma - d + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} s^{-1} \right) \\ \leq (d-1)d\gamma^2 \left(1 - \frac{\mu(x)}{C} \left(\frac{1-\gamma}{d-\gamma}\right)^{1-\gamma} \right) < 0. \end{aligned}$$

Thus, using (3.7), we also obtain, for $\left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \leq s \leq \frac{1-\gamma}{d-\gamma} \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}$ that

$$\begin{aligned} (d-1)d\gamma^2 + \frac{\gamma\mu(x)}{s^\gamma} \left(\gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \right) \left(\gamma - d + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} s^{-1} \right) \\ + \frac{1}{\theta} \left\{ \frac{\mu(x)}{s^\gamma} \left[\gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \right] - d\gamma \right\}^2 \leq 0. \end{aligned}$$

Hence, multiplying by $s^{2\gamma} \left(\gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \right)^{-2}$, we get that (3.6) holds true in this case.

iii) If $\frac{1-\gamma}{d-\gamma} \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} < s < \nu$, then $ds \geq \gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}$ and

$$(3.8) \quad -\frac{d\gamma s^\gamma \mu(x)}{\gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}}} + \gamma s^{\gamma-1} \mu(x) \leq 0.$$

Furthermore, since $(d-1)d\gamma^2 < 0$ and

$$\left| \frac{\mu(x)}{s^\gamma} \left[\gamma s + (1-\gamma) \left(\frac{\gamma}{C}\right)^{\frac{1}{1-\gamma}} \right] \right| \leq \|\mu\|_\infty d\nu^{1-\gamma},$$

for every $s \in \left(\frac{1-\gamma}{d-\gamma} \left(\frac{\gamma}{C} \right)^{\frac{1}{1-\gamma}}, \nu \right)$, we also obtain by (3.7) that

$$(d-1)d\gamma^2 + \frac{1}{\theta} \left\{ \frac{\mu(x)}{s^\gamma} \left[\gamma s + (1-\gamma) \left(\frac{\gamma}{C} \right)^{\frac{1}{1-\gamma}} \right] - d\gamma \right\}^2 \leq 0,$$

and consequently, multiplying by $s^{2\gamma} \left(\gamma s + (1-\gamma) \left(\frac{\gamma}{C} \right)^{\frac{1}{1-\gamma}} \right)^{-2}$, we get

$$\frac{d(d-1)s^{2\gamma}}{\left(s + (1-\gamma)\gamma^{\frac{\gamma}{1-\gamma}} C^{\frac{-1}{1-\gamma}} \right)^2} + \frac{1}{\theta} \left(\mu(x) - \frac{ds^\gamma}{s + (1-\gamma)\gamma^{\frac{\gamma}{1-\gamma}} C^{\frac{-1}{1-\gamma}}} \right)^2 \leq 0.$$

This and (3.8) imply that

$$\begin{aligned} & \frac{d(d-1)s^{2\gamma}}{\left(s + (1-\gamma)\gamma^{\frac{\gamma}{1-\gamma}} C^{\frac{-1}{1-\gamma}} \right)^2} - \frac{ds^\gamma \mu(x)}{s + (1-\gamma)\gamma^{\frac{\gamma}{1-\gamma}} C^{\frac{-1}{1-\gamma}}} \\ & + \gamma s^{\gamma-1} \mu(x) + \frac{1}{\theta} \left(\mu(x) - \frac{ds^\gamma}{s + (1-\gamma)\gamma^{\frac{\gamma}{1-\gamma}} C^{\frac{-1}{1-\gamma}}} \right)^2 \leq 0, \end{aligned}$$

for every $s \in \left(\frac{1-\gamma}{d-\gamma} \left(\frac{\gamma}{C} \right)^{\frac{1}{1-\gamma}}, \nu \right)$, which means that (3.6) is satisfied in this case. \square

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